

## TA session #2 ECON 342

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January 27, 2009

**Problem 1.** You plan to estimate following panel data model:

$$y_{it} = \mathbf{x}_{it}\beta + \varepsilon_{it}$$

with  $\varepsilon_{it} = \alpha_i + u_{it}$ . Re-write the model for all  $T$  periods as follows:

$$\mathbf{y}_i = \mathbf{X}_i\beta + \varepsilon_i$$

where:

$$\mathbf{y}_i = (y_{i1}, \dots, y_{iT})'; \quad \mathbf{u}_i = (u_{i1}, \dots, u_{iT})'$$
$$\mathbf{X}_i = \begin{pmatrix} \mathbf{x}_{i1} \\ \mathbf{x}_{i2} \\ \vdots \\ \mathbf{x}_{iT} \end{pmatrix}; \quad \varepsilon_i = \alpha_i \mathbf{i}_T + \mathbf{u}_i; \quad \mathbb{E}(\varepsilon_i \varepsilon_i') = \Omega$$

After long meditation you conclude that it is reasonable to assume that:

1.  $\mathbb{E}(u_{it}|\mathbf{x}_i, \alpha_i) = 0$  and  $\mathbb{E}(\alpha_i|\mathbf{x}_i) = 0$
2.  $\mathbb{E}(\mathbf{x}_i' \Omega^{-1} \mathbf{x}_i) = \mathbf{A}$  is nonsingular (has rank  $K = K_1 + \dots + K_M$ )
3. (a)  $\mathbb{E}(\mathbf{u}_i \mathbf{u}_i' | \mathbf{x}_i, \alpha_i) = \sigma_u^2 \mathbf{I}_T$ , and (b)  $\mathbb{E}(\alpha_i^2 | \mathbf{x}_i) = \sigma_\alpha^2$

**a)** Obtain the asymptotic properties of your RE estimator.

**b)** Your colleague suggests that (1), (2) and (3a) hold but (3b) does not. Are your estimates of  $\beta$  still valid?

*Solution.* Our assumptions imply:

$$\mathbb{E}(\alpha_i^2) = \mathbb{E}(\mathbb{E}(\alpha_i^2|\mathbf{x}_i)) = \sigma_\alpha^2 \quad (1)$$

$$\mathbb{E}(u_{it}^2) = \mathbb{E}(\mathbb{E}(u_{it}^2|\mathbf{x}_i, \alpha_i)) = \sigma_u^2 \quad (2)$$

$$\mathbb{E}(u_{it}u_{is}) = 0 \quad (3)$$

Thus, the diagonal elements of  $\Omega$  contain:

$$\mathbb{E}(\varepsilon_{it}^2) = \mathbb{E}((\alpha_i + u_{it})^2) = \mathbb{E}(\alpha_i^2) + \mathbb{E}(u_{it}^2) + 2\mathbb{E}(\alpha_i u_{it}) = \sigma_u^2 + \sigma_\alpha^2$$

while the diagonal elements are:

$$\mathbb{E}(\varepsilon_{it}\varepsilon_{is}) = \mathbb{E}((\alpha_i + u_{it})(\alpha_i + u_{is})) = \sigma_\alpha^2$$

therefore,

$$\Omega = \begin{pmatrix} \sigma_u^2 + \sigma_\alpha^2 & \sigma_\alpha^2 & \cdots & \sigma_\alpha^2 \\ \sigma_\alpha^2 & \ddots & 0 & \vdots \\ \vdots & & & \\ \sigma_\alpha^2 & \cdots & & \sigma_u^2 + \sigma_\alpha^2 \end{pmatrix} \quad (4)$$

Using,

$$\hat{\Omega} \xrightarrow{p} \Omega$$

we have:

$$\hat{\beta}_{RE} = \left[ \frac{1}{N} \sum_{i=1}^N \mathbf{x}_i' \hat{\Omega}^{-1} \mathbf{x}_i \right]^{-1} \frac{1}{N} \sum_{i=1}^N \mathbf{x}_i' \hat{\Omega}^{-1} \mathbf{y}_i \quad (5)$$

The limiting distribution of the RE estimator is obtained by writing:

$$\begin{aligned} \hat{\beta}_{RE} - \beta &= \left[ \frac{1}{N} \sum_{i=1}^N \mathbf{x}_i' \hat{\Omega}^{-1} \mathbf{x}_i \right]^{-1} \frac{1}{N} \sum_{i=1}^N \mathbf{x}_i' \hat{\Omega}^{-1} \varepsilon_i \\ \sqrt{N}(\hat{\beta}_{RE} - \beta) &= \left[ \frac{1}{N} \sum_{i=1}^N \mathbf{x}_i' \hat{\Omega}^{-1} \mathbf{x}_i \right]^{-1} \frac{1}{\sqrt{N}} \sum_{i=1}^N \mathbf{x}_i' \hat{\Omega}^{-1} \varepsilon_i \end{aligned}$$

Using the LLN and assumption (2) we have:

$$\left[ \frac{1}{N} \sum_{i=1}^N \mathbf{x}_i' \hat{\Omega}^{-1} \mathbf{x}_i \right]^{-1} \xrightarrow{p} \mathbf{A}^{-1}$$

and the CLT along with (1)-(3) yields,

$$\frac{1}{\sqrt{N}} \sum_{i=1}^N \mathbf{x}_i' \hat{\Omega}^{-1} \varepsilon_i \xrightarrow{p} N(\mathbf{0}, \mathbf{H})$$

with,

$$\mathbf{H} = \mathbb{E}(\mathbf{x}_i' \Omega^{-1} \varepsilon_i \varepsilon_i' \Omega^{-1} \mathbf{x}_i) = \mathbb{E}(\mathbf{x}_i' \Omega^{-1} \mathbb{E}(\varepsilon_i \varepsilon_i' | \mathbf{x}_i) \Omega^{-1} \mathbf{x}_i) = \mathbb{E}(\mathbf{x}_i' \Omega^{-1} \mathbf{x}_i)$$

which together imply:

$$\begin{aligned} \sqrt{N}(\hat{\beta}_{RE} - \beta) &\xrightarrow{d} N(\mathbf{0}, \underbrace{\mathbf{A}^{-1} \mathbf{H} \mathbf{A}^{-1}}_{\mathbf{A}^{-1}}) \\ &= N(\mathbf{0}, \mathbf{A}^{-1}) \end{aligned}$$

When (3b) does not hold we have

$$\mathbb{E}(\alpha_i^2 | \mathbf{x}_i) = f(\mathbf{x}_i),$$

therefore,

$$\begin{aligned} \mathbb{E}(\varepsilon_{it}^2) &= \sigma_u^2 + f(\mathbf{x}_i) \\ \mathbb{E}(\varepsilon_{it} \varepsilon_{is}) &= f(\mathbf{x}_i) \end{aligned}$$

In this case,

$$\mathbb{E}(\varepsilon_i \varepsilon_i' | \mathbf{x}_i) = \begin{pmatrix} \sigma_u^2 + f(\mathbf{x}_i) & f(\mathbf{x}_i) & \cdots & f(\mathbf{x}_i) \\ f(\mathbf{x}_i) & \ddots & 0 & \vdots \\ \vdots & & & \\ f(\mathbf{x}_i) & \cdots & & \sigma_u^2 + f(\mathbf{x}_i) \end{pmatrix}$$

which does not have the form of 4. The usual RE estimator 5 is still consistent but the variance-covariance matrix is no longer valid. In this case, the CLT along with (1)-(3a) yields,

$$\frac{1}{\sqrt{N}} \sum_{i=1}^N \mathbf{x}_i' \hat{\Omega}^{-1} \varepsilon_i \xrightarrow{p} N(\mathbf{0}, \mathbf{H})$$

where,

$$\mathbf{H} = \mathbb{E}(\mathbf{x}_i' \Omega^{-1} \varepsilon_i \varepsilon_i' \Omega^{-1} \mathbf{x}_i)$$

Then,

$$\sqrt{N}(\hat{\beta}_{RE} - \beta) \xrightarrow{d} N(\mathbf{0}, \mathbf{A}^{-1} \mathbf{H} \mathbf{A}^{-1})$$

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**Problem 2.** Consider the model from the previous problem. After performing a Hausman test you realize that you should use a fixed effect estimator.

a) You decide to estimate your model using the difference estimator to eliminate the unobserved effect  $\alpha_j$ . Under what conditions is your estimator consistent?

b) What is the variance-covariance matrix of your estimator?

*Solution.* Taking differences we have:

$$\begin{array}{ll} y_{i1} = \mathbf{x}_{i1}\beta + \alpha_i + u_{i1} & \cdot \\ y_{i2} = \mathbf{x}_{i2}\beta + \alpha_i + u_{i2} & y_{i2} - y_{i1} = (\mathbf{x}_{i2} - \mathbf{x}_{i1})\beta + (u_{i2} - u_{i1}) \\ \vdots & \Rightarrow \vdots \\ y_{i,T-1} = \mathbf{x}_{i,T-1}\beta + \alpha_i + u_{i,T-1} & y_{i,T-1} - y_{i,T-2} = (\mathbf{x}_{i,T-1} - \mathbf{x}_{i,T-2})\beta + (u_{i,T-1} - u_{i,T-2}) \\ y_{iT} = \mathbf{x}_{iT}\beta + \alpha_i + u_{iT} & y_{iT} - y_{i,T-1} = (\mathbf{x}_{iT} - \mathbf{x}_{i,T-1})\beta + (u_{iT} - u_{i,T-1}) \end{array}$$

then the model 'loses'  $t = 1$  and for  $t \geq 2$  we have:

$$\Delta y_{it} = \Delta \mathbf{x}_{it}\beta + \Delta u_{it}$$

Stacking all  $T - 1$  equations we can re-write the system of equations as:

$$\Delta \mathbf{y}_i = \Delta \mathbf{x}_i\beta + \Delta \mathbf{u}_i$$

The pooled OLS estimator from this model will be consistent if:

$$\mathbb{E}(\Delta \mathbf{x}'_i \Delta \mathbf{u}_i) = \mathbf{0}$$

Note that,

$$\Delta \mathbf{x}'_i \Delta \mathbf{u}_i = (\Delta \mathbf{x}'_{i2}, \Delta \mathbf{x}'_{i3}, \dots, \Delta \mathbf{x}'_{iT}) \times \begin{pmatrix} \Delta u_{i2} \\ \Delta u_{i3} \\ \vdots \\ \Delta u_{iT} \end{pmatrix}$$

which implies that we need:

$$\mathbb{E}(\Delta \mathbf{x}'_{it} \Delta u_{it}) = \mathbb{E}((\mathbf{x}_{it} - \mathbf{x}_{i,t-1})(u_{it} - u_{i,t-1})) = 0; \text{ for } t = 2, \dots, T$$

which will fail if  $u_{it}$  is correlated with  $\mathbf{x}_{it}$  or  $\mathbf{x}_{i,t-1}$ , and  $u_{i,t-1}$  with  $\mathbf{x}_{it}$  which is the same as saying  $u_{it}$  is correlated with  $\mathbf{x}_{i,t+1}$ . For consistency of our estimator we can set our first assumption as follows:

$$\mathbb{E}(u_{it} | \mathbf{x}_{t-1}, \mathbf{x}_t, \mathbf{x}_{t+1}) = 0, \text{ for } t = 2, \dots, T$$

A stronger assumption would be to assume strong exogeneity,

$$\mathbb{E}(\Delta u_{it} | \Delta \mathbf{x}_2, \dots, \Delta \mathbf{x}_T) = 0, \text{ for } t = 2, \dots, T$$

With this assumption at hand we have:

$$\beta = [\mathbb{E}(\Delta \mathbf{x}'_i \Delta \mathbf{x}_i)]^{-1} \Delta \mathbf{x}'_i \Delta \mathbf{y}_i$$

For  $[\mathbb{E}(\Delta \mathbf{x}'_i \Delta \mathbf{x}_i)]^{-1} = \left[ \sum_{t=2}^T \mathbb{E}(\Delta \mathbf{x}'_{it} \Delta \mathbf{x}_{it}) \right]^{-1}$  to be well defined we need that it is invertible, thus we cannot have a non-time varying variable in  $\mathbf{x}_i$ . To obtain the FE estimator we write:

$$\hat{\beta}_{FE} = \left[ \frac{1}{N} \sum_{i=1}^N \sum_{t=2}^T \Delta \mathbf{x}'_{it} \Delta \mathbf{x}_{it} \right]^{-1} \frac{1}{N} \sum_{i=1}^N \sum_{t=2}^T \Delta \mathbf{x}'_{it} \Delta y_{it}$$

To obtain the asymptotic variance-covariance matrix of this estimator we need to make some assumptions about  $u_{it}$ . We will keep it simple (for now) and assume that the error term is serially uncorrelated and conditionally homoskedastic. As usual, re-write the estimator as:

$$\sqrt{N}(\hat{\beta}_{FE} - \beta) = \left[ \frac{1}{N} \sum_{i=1}^N \sum_{t=2}^T \Delta \mathbf{x}'_{it} \Delta \mathbf{x}_{it} \right]^{-1} \frac{1}{\sqrt{N}} \sum_{i=1}^N \sum_{t=2}^T \Delta \mathbf{x}'_{it} \Delta \mathbf{u}_{it}$$

Using the CLT we know,

$$\frac{1}{\sqrt{N}} \sum_{i=1}^N \sum_{t=2}^T \Delta \mathbf{x}'_{it} \Delta \mathbf{u}_{it} \xrightarrow{p} N(\mathbf{0}, \mathbf{H})$$

with,

$$\mathbf{H} = \mathbb{E}(\Delta \mathbf{x}'_i \Delta \mathbf{u}_i \Delta \mathbf{u}'_i \Delta \mathbf{x}_i) \quad (6)$$

Under our assumptions we can develop this further. Notice that

$$\Omega = \mathbb{E}(\mathbf{u}_i \mathbf{u}'_i)$$

has diagonal elements equal to:

$$\mathbb{E}(\Delta u_{it}^2) = \mathbb{E}(u_{it}^2 + u_{i,t-1}^2 - 2u_{it}u_{i,t-1}) = 2\sigma_u^2$$

and non-diagonal elements equal to,

$$\mathbb{E}(\Delta u_{it} \Delta u_{i,t-j}) = \begin{cases} \mathbb{E}(-u_{i,t-1}^2) = -\sigma_u^2, & \text{when } j = 1; \\ 0, & \text{when } j > 1 \end{cases}$$

Then,

$$\Omega = \sigma_u^2 \begin{pmatrix} 2 & -1 & 0 & \cdots & 0 \\ -1 & 2 & & & \\ 0 & & \ddots & & \\ & & & & -1 \\ 0 & & & -1 & 2 \end{pmatrix} = \sigma_u^2 \Sigma$$

which implies that 6 can be written as:

$$\mathbf{H} = \mathbb{E} (\Delta \mathbf{x}'_i \Delta \mathbb{E} (\mathbf{u}_i \Delta \mathbf{u}'_i | \mathbf{x}_i) \Delta \mathbf{x}_i) = \sigma_u^2 \mathbb{E} (\Delta \mathbf{x}'_i \Sigma \Delta \mathbf{x}_i)$$

Finally, we conclude that:

$$\sqrt{N}(\hat{\beta}_{FE} - \beta) \xrightarrow{d} N(\mathbf{0}, \mathbf{A}^{-1} \mathbf{H} \mathbf{A}^{-1})$$

where,

$$\mathbf{A}^{-1} \mathbf{H} \mathbf{A}^{-1} = \sigma_u^2 [\mathbb{E} (\Delta \mathbf{x}'_i \Delta \mathbf{x}_i)]^{-1} \mathbb{E} (\Delta \mathbf{x}'_i \Sigma \Delta \mathbf{x}_i) [\mathbb{E} (\Delta \mathbf{x}'_i \Delta \mathbf{x}_i)]^{-1}$$

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